**Example 10-13:** If  $b_0 = 5$ ,  $a_1 = -0.8$ , and  $\hat{\omega}_0 = 2\pi/10$ , the transient component in (??) is

$$y_{t}[n] = \left(\frac{-4}{-0.8 - e^{j0.2\pi}}\right)(-0.8)^{n}u[n]$$
  
= 2.3351e^{-j0.3502}(-0.8)^{n}u[n]  
= 2.1933(-0.8)^{n}u[n] - j0.8012(-0.8)^{n}u[n]

Similarly, the steady-state component in (??) is

$$y_{ss}[n] = \left(\frac{5}{1+0.8e^{-j0.2\pi}}\right)e^{j0.2\pi n}u[n]$$
  
= 2.9188 $e^{j0.2781}e^{j0.2\pi n}u[n]$   
= 2.9188 cos (0.2\pi n + 0.2781) u[n] + j 2.9188 sin (0.2\pi n + 0.2781) u[n]

Figure ?? shows the real parts of the total output (a), the transient component (b), and the steady-state component (c). The signals all start at n = 0 which is when the complex exponential is applied at the input. Note how the transient component  $(-0.8)^n$  oscillates, but dies away, which explains why the steady-state component eventually equals the total output. In Fig. ??, y[n] in (a) and  $y_{ss}[n]$  in (c) look identical for n > 15.





On the other hand, if the pole were at z = 1.1, the system would be unstable and the output would "blow up" as shown in Fig. 10-15. In this case, the output contains a term  $(1.1)^n$  that eventually dominates and grows without bound.