

**PROBLEM:**

The diagram in Figure 1 depicts a *cascade connection* of two linear time-invariant systems; i.e., the output of the first system is the input to the second system, and the overall output is the output of the second system.

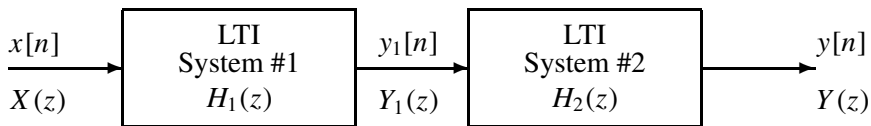


Figure 1: Cascade connection of two LTI systems.

- Use  $z$ -transforms to show that the system function of the overall system (from  $x[n]$  to  $y[n]$ ) is  $H(z) = H_2(z)H_1(z)$ , where  $Y(z) = H(z)X(z)$ .
- Derive a condition on  $H(z)$  that guarantees that the output signal will always be equal to the input signal.
- Suppose that System #1 is an FIR filter described by the difference equation  $y_1[n] = x[n] + \frac{5}{6}x[n-1]$  and System #2 is described by the system function  $H_2(z) = 1 - 2z^{-1} + z^{-2}$ . Determine the system function of the overall cascade system.
- Obtain a single difference equation that relates  $y[n]$  to  $x[n]$  in Figure 1.
- Plot the poles and zeros of  $H(z)$  in the complex  $z$ -plane.
- If System #1 is the difference equation:  $y_1[n] = x[n] + \frac{5}{6}x[n-1]$ , find a system function  $H_2(z)$  so that output of the cascaded system will always be equal to its input. In other words, find  $H_2(z)$  which will undo the filtering action of  $H_1(z)$ . This is called *deconvolution*.