

**PROBLEM:**

An LTI system has the following system function:

$$H(z) = \frac{1 - z^{-2}}{1 + 0.5z^{-1}}.$$

The following questions cover most of the ways available for analyzing IIR discrete-time systems.

- Plot the poles and zeros of  $H(z)$  in the  $z$ -plane.
- Determine the difference equation that is satisfied by the general input  $x[n]$  and the corresponding output  $y[n]$  of the system.
- Use  $z$ -transforms to determine the impulse response  $h[n]$  of the system; i.e., the output of the system when the input is  $x[n] = \delta[n]$ .
- Determine an expression for the frequency response  $H(e^{j\hat{\omega}})$  of the system.
- Use the frequency response function to determine the output  $y_1[n]$  of the system when the input is

$$x_1[n] = 2 \cos(\pi n) \quad -\infty < n < \infty.$$

- Use the  $z$ -transform to determine the output  $y_2[n]$  when the input is

$$x_2[n] = 2 \cos(\pi n)u[n] = \begin{cases} 2(-1)^n & n \geq 0 \\ 0 & n < 0. \end{cases}$$