A linear time-invariant filter is described by the difference equation

$$
y[n]=x[n]+x[n-1]-x[n-3]-x[n-4]
$$

(a) Derive a simple expression for $\mathcal{H}(\hat{\omega})$, the frequency response of this system.
(b) Sketch the frequency response (magnitude and phase) versus frequency for $-\pi \leq \hat{\omega} \leq \pi$.
(c) What is the output if the input is

$$
x[n]=\cos [0.3 \pi(n-2)]-3 \cos [0.2 \pi n]
$$

